

## Lecture 11 Outline

**Reading:** *text*, §8

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1. Role-based Access Control (RBAC)
  - a. Definition of role
  - b. Partitioning as job function
  - c. Containment
2. Problem with instantiation of Bell-LaPadula Model
  - a. Covert channel example: what is “writing”?
  - b. Composition of lattices
  - c. Principles of autonomy and security
3. Deterministic noninterference
  - a. Model of system
  - b. Example
  - c. Relationship of output to states
  - d. Projections and purge functions
4. Alternative definition of security policy
  - a. Output-consistent
  - b. Security policy
  - c. Alternate projection function
  - d. Noninterference-secure with respect to the policy  $r$
5. Unwinding Theorem
  - a. Locally respects
  - b. Transition-consistent
  - c. Unwinding theorem
6. Access Control Matrix interpretation
  - a. Model
  - b. ACM conditions
  - c. Policy conditions
  - d. Result
7. Policies that change over time
  - a. Generalization of noninterference
  - b. Example
8. Composing deterministic, noninterference-secure systems

**Table of Notation**

<i>notation</i>	<i>meaning</i>
$C$	set of commands $(s, z)$ , where $s$ executes operation $z$
$C^*$	set of sequences of commands
$\pi''$	generalized noninterference analogue to the purge function $\pi_{G,A}$
$\epsilon$	empty string
$c_s$	sequence of commands
$P(c, \sigma_i)$	output from command $c$ being executed in state $\sigma_i$
$P^*(c_s, \sigma_i)$	outputs when command sequence $c_s$ is executed in state $\sigma_i$
$proj(s, c_s, \sigma_i)$	set of outputs in $P^*(c_s, \sigma_i)$ that subject $s$ is authorized to see
$w$	sequence of elements of $C$ leading up to current state
$cando(w, s, z)$	true if $s$ can execute $z$ in current state
$pass(s, z)$	give $s$ right to execute $z$
$w_n$	$v_1, \dots, v_n$ where $v_i \in C^*$
$prev(w_n)$	$w_{n-1}$
$last(w_n)$	$v_n$
$\pi_L$	projection function deleting all <i>High</i> inputs from trace