# ECS 235B, Lecture 15

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## Constraint-Based Model (Yu-Gligor)

- Framed in terms of users accessing a server for some services
- User agreement: describes properties that users of servers must meet
- *Finite waiting time policy*: ensures no user is excluded from using resource

#### User Agreement

- Set of constraints designed to prevent denial of service
- S<sub>seq</sub> sequence of all possible invocations of a service
- $U_{seq}$  set of sequences of all possible invocations by a user
- $U_{li,seq} \subseteq U_{seq}$  that user  $U_i$  can invoke
  - *C* set of operations *U<sub>i</sub>* can perform to consume service
  - *P* set of operations to produce service user *U<sub>i</sub>* consumes
  - p < c means operation  $p \in P$  must precede operation  $c \in C$
  - A<sub>i</sub> set of operations allowed for user U<sub>i</sub>
  - R<sub>i</sub> set of relations between every pair of allowed operations for U<sub>i</sub>

### Example

Mutually exclusive resource

- *C* = { *acquire* }
- *P* = { *release* }
- For *p*<sub>1</sub>, *p*<sub>2</sub>, *A<sub>i</sub>* = { *acquire<sub>i</sub>*, *release<sub>i</sub>* } for *i* = 1, 2
- For *p*<sub>1</sub>, *p*<sub>2</sub>, *R<sub>i</sub>* = { ( *acquire<sub>i</sub>* < *release<sub>i</sub>* ) } for *i* = 1, 2

## Sequences of Operations

- $U_i(k)$  initial subsequence of  $U_i$  of length k
  - $n_o(U_i(k))$  number of times operation o occurs in  $U_i(k)$
- $U_i(k)$  safe if the following 2 conditions hold:
  - if  $o \in U_{i,seq}$ , then  $o \in A_i$ ; and
    - That is, if  $U_i$  executes  $o_i$ , it must be an allowed operation for  $U_i$
  - for all k, if  $(o < o') \in R_i$ , then  $n_o(U_i(k)) \ge n_{o'}(U_i(k))$ 
    - That is, if one operation precedes another, the first one must occur more times than the second

#### **Resources of Services**

- $s \in S_{seq}$  possible sequence of invocations of services
- *s* blocks on condition *c* 
  - May be waiting forservice to become available, or processing some response, etc.
- $o_i^*(c)$  represents operation  $o_i$  blocked, waiting for c to become true
  - When execution results,  $o_i(c)$  represents operation
  - Note that when c becomes true,  $o_i^*(c)$  may not resume immediately

#### **Resources of Services**

- s(0) initial subsequence of s up to operation  $o_i^*(c)$
- s(k) subsequence of operations between k-1<sup>st</sup>, k<sup>th</sup> time c becomes true after o<sub>i</sub><sup>\*</sup>(c)
- $o_i^*(c) \rightarrow o_i(c)$ :  $o_i$  blocks waiting on c at end of s(0), resumes operation at end of s(k)
- $S_{seq}$  live if for every  $o_i^*(c)$  there is a set of subsequences s(0), ..., s(k)such that it is initial subsequence of some  $s \in S_{seq}$  and  $o_i^*(c) \rightarrow s(k) o_i(c)$

### Example

• Mutually exclusive resource; consider sequence

( $acquire_i$ ,  $release_i$ ,  $acquire_i$ ,  $acquire_i$ ,  $release_i$ ) with  $acquire_i$ ,  $release_i \in A_i$ , ( $acquire_i$ ,  $release_i$ )  $\in R_i$ ;  $o = acquire_i$ ,  $o' = release_i$ 

- $U_i(1) = (acquire_i) \Rightarrow n_o(U_i(1)) = 1, n_{o'}(U_i(1)) = 0$
- $U_i(2) = (acquire_i, release_i) \Rightarrow n_o(U_i(2)) = 1, n_{o'}(U_i(2)) = 1$
- $U_i(3) = (acquire_i, release_i, acquire_i) \Rightarrow n_o(U_i(3)) = 2, n_{o'}(U_i(3)) = 1$
- $U_i(4) = (acquire_i, release_i, acquire_i, acquire_i) \Rightarrow$

 $n_o(U_i(4)) = 3, n_{o'}(U_i(4)) = 1$ 

•  $U_i(5) = (acquire_i, release_i, acquire_i, acquire_i, release_i) \Rightarrow$ 

 $n_o(U_i(5)) = 3, n_{o'}(U_i(5)) = 2$ 

• As  $n_o(U_i(k)) > n_{o'}(U_i(k))$  for k = 1, ..., 5, the sequence is safe

## Example (con't)

- Let *c* be true whenever resource can be released
  - That is, initially and whenever a *release*, operation is performed
- Consider sequence: (acquire<sub>1</sub>, acquire<sub>2</sub>\*(c), release<sub>1</sub>, release<sub>2</sub>, ..., acquire<sub>k</sub>, acquire<sub>k+1</sub>(c), release<sub>k</sub>, release<sub>k+1</sub>, ...)
- For all  $k \ge 1$ ,  $acquire_i^*(c) \rightarrow s(1) acquire_{k+1}(c)$ , so this is live sequence
  - Here, *acquire*<sub>k+1</sub>(c) occurs between *release*<sub>k</sub> and *release*<sub>k+1</sub>

## Expressing User Agreements

- Use temporal logics
- Symbols
  - □: henceforth (the predicate is true and will remain true)
  - \$\lapha: eventually (the predicate is either true now, or will become true in the future)
  - →: will lead to (if the first part is true, the second part will eventually become true); so A → B is shorthand for A ⇒ ◊B

### Example

- Acquiring and releasing mutually exclusive resource type
- User agreement: once a process is blocked on an *acquire* operation, enough *release* operations will release enough resources of that type to allow blocked process to proceed

#### service resource\_allocator

User agreement

 $in(acquire) \rightarrow ((\Box \diamondsuit (\#active\_release > 0) \lor (free \ge acquire.n)))$ 

• When a process issues an *acquire* request, at some later time at least 1 *release* operation occurs, and enough resources will be freed for the requesting process to acquire the needed resources

## Finite Waiting Time Policy

- *Fairness policy*: prevents starvation; ensures process using a resource will not block indefinitely if given the opportunity to progress
- *Simultaneity policy*: ensures progress; provides opportunities process needs to use resource
- User agreement: see earlier
- If these three hold, no process will wait an indefinite time before accessing and using the resource

### Example

 Continuing example ... these and above user agreement ensure no indefinite blocking

#### sharing policies

#### fairness

 $(at(acquire) \land \Box \diamondsuit ((free \ge acquire.n) \land (#active = 0))) \rightarrow after(acquire)$  $(at(release) \land \Box \diamondsuit (#active = 0)) \rightarrow after(release)$ 

#### simultaneity

 $(in(acquire) \land (\Box \diamondsuit (free \ge acquire.n)) \land (\Box \diamondsuit (\#active = 0))) \rightarrow$ 

 $((free \ge acquire.n) \land (#active = 0))$ 

 $(in(release) \land \Box \diamondsuit (#active_release > 0)) \rightarrow (free \ge acquire.n)$ 

#### Service Specification

- Interface operations
- Private operations not available outside service
- Resource constraints
- Concurrency constraints
- Finite waiting time policy

### Example:

• Interface operations of the resource allocation/deallocation example interface operations

```
acquire(n: units)
exception conditions: quota[id] < own[id] + n
effects: free' = free - n
own[id]' = own[id] + n
release(n: units)
exception conditions: n > own[id]
effects: free' = free + n
own[id]' = own[id] - n
```

## Example (con't)

- Resource constrains of the resource allocation/deallocation example resource constraints
- 1.  $\Box$  ((*free*  $\geq$  0)  $\land$  (*free*  $\leq$  *size*))
- 2.  $(\forall id) [\Box(own[id] \ge 0) \land (own[id] \le quota[id]))]$
- 3. (free = N)  $\Rightarrow$  ((free = N) UNTIL (after(acquire)  $\lor$  after(release)))
- 4.  $(\forall id) [(own[id] = M) \Rightarrow ((own[id] = M) UNTIL (after(acquire) \lor after(release)))]$

## Example (*con't*)

Concurrency constraints of the resource allocation/deallocation example

#### concurrency constraints

- 1.  $\Box$  (#active  $\leq$  1)
- 2.  $(\#active = 1) \rightarrow (\#active = 1)$

### Denial of Service

- Service specification policies, user agreements prevent denial of service *if enforced*
- These do *not* prevent a long wait time; they simply ensure the wait time is finite

### State-Based Model (Millen)

- Unlike constraint-based model, allows a maximum waiting time to be specified
- Based on resource allocation system, denial of service base that enforces its policies

### Resource Allocation System Model

- *R* set of resource types
- For each r ∈ R, number of resource units (capacity, c(r)) is constant; a process can hold a unit for a maximum holding time m(r)
- *P* set of processes
- For each  $p \in P$ , state is *running* or *sleeping* 
  - When allocated a resource, process is running
  - Multiple process can be in running state simultaneously
  - Each p has upper bound it can be in running state before being interrupted, if only by CPU quantum q
  - Example: if CPU considered a resource, m(CPU) = q

#### Allocation Matrix

- Rows represent processes; columns represent resources
  - $A: P \times R \rightarrow \mathbb{N}$  is matrix
  - For  $p \in P$ ,  $r \in R$ ,  $A_p(r)$  is number of resource units of type r acquired by p
  - As at most c(r) of resource type r exist, at most that many can be allocated at any time

R1: The system cannot allocate more instances of a resource type than it has:

$$(\forall r \in R)[\sum_{p \in P} A_p(r) \le c(r)]$$

#### More About Resources

- $T: P \rightarrow \mathbb{N}$  is system time when resource assignment was last changed
  - Think of it as a time vector, each element belonging to one process
- $Q^S: P \times R \rightarrow \mathbb{N}$  is matrix of required resources for each process, not including the resources it already holds
  - So Q<sup>s</sup><sub>p</sub>(r) means the number of units of resource type r that process p may need to complete
- $Q^T: P \times R \rightarrow \mathbb{N}$  is matrix of how much longer each process p needs the units of resource r
- Predicates *running(p)* true if *p* is in running state; *asleep(p)* true otherwise

R2: A currently running process must not require additional resources to run running(p) =>  $(\forall r \in R)[Q_{\rho}^{s}(r) = 0]$ 

#### States, State Transitions

- Current state of system is (A, T, Q<sup>S</sup>, Q<sup>T</sup>)
- State transition  $(A, T, Q^S, Q^T) \rightarrow (A', T', Q^{S'}, Q^{T'})$ 
  - We only care about treansitions due to allocation, deallocation of resources
- Three relevant types of transitions
  - Deactivation transition:  $running(p) \rightarrow asleep'(p)$ ; process stops execution
  - Activation transition: asleep(p) → running'(p); process starts or resumes execution
  - Reallocation transition: transition in which p has resource allocation changed; can only occur when asleep(p)

#### Constraints

R3: Resource allocation does not affect allocations of a running process:

 $(running(p) \land running'(p)) \Rightarrow (A_{p}' = A_{p})$ 

R4: T(p) changes only when resource allocation of p changes:

$$(A_{\rho}'(\mathsf{CPU}) = A_{\rho}(\mathsf{CPU})) \Rightarrow (T'(p) = T(p))$$

R5: Updates in time vector increase value of element being updated:  $(A_{p}'(CPU) \neq A_{p}(CPU)) => (T'(p) > T(p))$ 

#### Constraints

R6: When *p* reallocated resources, allocation matrix updated before *p* resumes execution:

$$asleep(p) \Rightarrow Q_{\rho}^{S}' = Q_{\rho}^{S} + A_{\rho} - A_{\rho}'$$

R7: When a process is not running, the time it needs resources does not change:

$$asleep(p) \Rightarrow Q_{p}^{T}' = Q_{p}^{T}$$

R8: when a process ceases to execute, the only resource it *must* surrender is the CPU:

 $(running(p) \land asleep'(p)) \Rightarrow A_{p}'(r) = A_{p}(r)-1$  if r = CPU $(running(p) \land asleep'(p)) \Rightarrow A_{p}'(r) = A_{p}(r)$  otherwise

### Resource Allocation System

- A system in a state (A, T, Q<sup>S</sup>, Q<sup>T</sup>) such that:
  - State satisfies constraints R1, R2
  - All state transitions constrained to meet R3-R8

## Denial of Service Protection Base (DPB)

- A mechanism that is tamperproof, cannot be prevented from operating, and guarantees authorized access to resources it controls
- Four parts:
  - Resource allocation system (see earlier)
  - Resource monitor
  - Waiting time policy
  - User agreement (see earlier; constraints apply to changes in allocation when process transitions from running(p) to asleep(p)

#### **Resource Monitor**

- Controls allocation, deallocation of resources and the timing
- $Q_{p}^{s}$  is feasible if  $(\forall i)[Q_{p}^{s}(r_{i}) + A_{p}(r_{i}) \leq c(r_{i})] \land Q_{p}^{s}(CPU) \leq 1$ 
  - If the total number of resources it will be allocated will always be no more than the capacity of that resource, and no more than 1 CPU is requested
- $T_p$  is feasible if  $(\forall i)[T_p(r_i) \le max(r_i)]$ 
  - Here, max(r<sub>i</sub>) max time a process must wait for its needed allocation of units of resource type i

### Waiting Time Policy

- Let  $\sigma = (A, T, Q^{S}, Q^{T})$
- Example finite waiting time policy:

 $(\forall p, \sigma)(\exists \sigma')[running'(p) \land (T'(p) \ge T(p))]$ 

- For every process and state, there is a future state in which p is executing and has been allocated resources
- Example maximum waiting time policy:

 $(\exists M)(\forall p, \sigma)(\exists \sigma')[running'(p) \land (0 < T'(p) - T(p) \le M)]$ 

• There is an upper bound *M* to how long it takes every process to reach a future state in which it is executing and has been allocated resources

### Two Additional Constraints

In addition to all these, a DPB must satisfy these constraints:

- 1. Each process satisfying user agreement constraints will progress in a way that satisfies the waiting time policy
- 2. No resource other than the CPU is deallocated from a process unless that resource is no longer needed

$$(\forall i)[r_i \neq \text{CPU} \land A_p(r_i) \neq 0 \land A_p'(r_i) = 0] \Rightarrow Q^T_p(r_i) = 0$$

## Example: DPB

- Assume system has 1 CPU
- Assume maximum waiting time policy in place
- 3 parts to user agreement:
  - $Q_{p}^{s}$ ,  $T_{p}$  are *feasible*
  - Process in running state executes for a minimum amount of time before it transitions to a non-running state
  - If process requires resource type, and enters a non-running state, the time it needs the resource for is decreased by the amount of time it was in the previous running state; that is,

 $Q_{p}^{T} \neq \mathbf{0} \land running(p) \land asleep'(p) \Rightarrow (\forall r \in R)[Q_{p}^{T}(r) \leq max(0, max_{r} Q_{p}^{T}(r) - (T'(p) - T(p)))]$ 

## Example: System

- *n* processes, round robin scheduler with quantum *q*
- Initially no process has any resources
- Resource monitor selects process *p* to give resources to
  - p executes until  $Q_p^T = \mathbf{0}$  or monitor concludes  $Q_p^S$  or  $T_p$  is not feasible
- Goal: show there will be no denial of service in this system because
  - a) no resource  $r_i$  is deallocated from p for which  $Q_p^s$  is feasible until  $Q_p^T = 0$ ; and
  - b) there is a maximum time for each round robin cycle

## Claim (a)

- Before *p* selected, no process has any resources allocated to it
  - So next process with  $Q_{p}^{S}$  and  $T_{p}$  feasible is selected
  - It runs until it enters the *asleep* state or *q*, whichever is shorter
  - If in *asleep* state, process is done
  - If q, monitor gives p another quantum of running time; this repeats until  $Q_p^T = 0$ , and then p needs no more resources
- Let *m*(*r*) be maximum time any process will hold resources of type *r* 
  - Let  $M(r) = max_r m(r)$
- As  $Q_{\rho}^{s}$  and  $T_{\rho}$  feasible, M upper bound for all elements of  $Q_{\rho}^{T}$ 
  - d = min(q, minimum time before p transitions to asleep state); exists because a
    process in running state executes for a minimum amount of time before it transitions
    to a non-running state

## Claim (a) (con't)

- As  $Q_{p}^{s}$  and  $T_{p}$  feasible, M upper bound for all elements of  $Q_{p}^{T}$
- *d* = *min*(*q*, minimum time before *p* transitions to *asleep* state)
  - Exists because a process in running state executes for a minimum amount of time before it transitions to a non-running state
- At end of each quantum, m'(r) = m(r) d
  - By third part of user agreement
- So after *floor*(M/d + 1) quanta,  $Q_{p}^{T} = \mathbf{0}$ 
  - So no resources deallocated until  $(\forall i) Q_{p}^{T}(r_{i}) = 0$

## Claim (b)

- t<sub>a</sub> is time between resource monitor beginning cycle and when it has allocated required resources to p
- Resource monitor then allocates CPU resource to p; call this time  $t_{CPU}$ 
  - Done between each quantum
- When p completes, all its resources deallocated; this takes time  $t_d$
- As  $Q_p^s$  and  $T_p$  feasible, time needed to run p, including time to deallocate all resources, is:

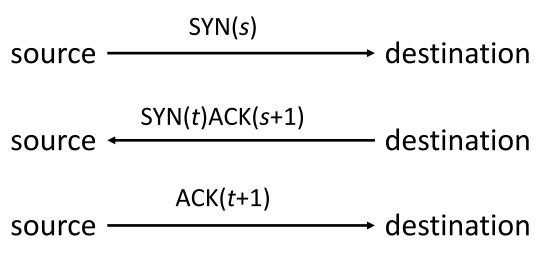
$$t_a + floor(M/d + 1)(q + t_{CPU}) + t_d$$

- So for *n* processes, maximum time cycle will take is *n* times this
- Thus, there is a maximum time for each round robin cycle

## Availability and Network Flooding

- Access over Internet must be unimpeded
  - Context: flooding attacks, in which attackers try to overwhelm system resources
- If many sources flood a target, it's a *distributed denial of service attack*

#### TCP 3-Way Handshake and Availability



- Normal three-way handshake to initiate connection
- Suppose source never sends third message (the last ACK)
  - Destination holds information about pending connection for a period of time before the space is released

## Analysis

- Consumption of bandwidth
  - If flooding overwhelms capacity of physical network medium, SYNs from legitimate handshake attempts may not be able to reach the target
- Absorption of resources on destination host
  - Flooding fills up memory space for pending connections, causing SYNs from legitimate handshake attempts to be discarded
- In terms of the models:
  - Waiting time is the time that destination waits for ACK from source
  - Fairness policy must assure host waiting for ACK (resource) will receive (acquire) it

## Analysis in Terms of Model

- Waiting time is the time that destination waits for ACK from source
- Fairness policy must assure host waiting for ACK (resource) will receive (acquire) it
  - But goal of attack is to make sure it never arrives
- Yu-Gligor model: finite wait time does not hold
  - So model says denial of service can occur
- Millen model:  $T_p(ACK) > max(ACK)$ 
  - *max*(ACK) is the time-out period for pending connections
  - So model says denial of service can occur

#### Countermeasures

- Focus on ensuring resources needed for legitimate handshakes to complete are available
  - So every legitimate client gets access to server
- First approach: manipulate opening of connection at end point
  - If focus is to ensure connection attempts will succeed at some time, focus is really on waiting time
  - Otherwise, focus is on user agreement
- Second approach: control which packets, or rate at which packets, sent to destination
  - Focus is on implicit user agreements

#### Intermediate Systems

- Approach is to reduce consumption of resources on destination by diverting or eliminating illegitimate traffic so only legitimate traffic reaches destination
  - Done at infrastructure level
- Example: Cisco routers try to establish connection with source (TCP intercept mode)
  - On success, router does same with intended destination, merges the two
  - On failure, short time-out protects router resources and target never sees flood

## Track Connection Status

- Use network monitor to track status of handshake
- Example: *synkill* monitors traffic on network
  - Classifies IP addresses as not flooding (good), flooding (bad), unknown (new)
  - Checks IP address of SYN
    - If good, packet ignored
    - If bad, send RST to destination; ends handshake, releasing resources
    - If new, look for ACK or RST from same source; if seen, change to good; if not seen, change to bad
  - Periodically discard stale good addresses

#### Intermediate Systems near Sources

- D-WARD relies on routers close to the sources to block attack
  - Reduces congestion in network without interfering with legitimate traffic
- Placed at gateways of possible sources to examine packets leaving (internal) network and going to Internet
- Deployed on systems in research lab for 4 months
  - First month: large number of false alerts
  - Tuning D-WARD parameters reduced this number

#### D-WARD: Observation Component

- Has set of legitimate internal addresses
- Gathers statistics on packets leaving network, discarding packets without legitimate addresses
- Tracks number of simultaneous connections to each remote destination
  - Unusually large number may indicate attack from this network
- Examines connections with large amount of outgoing traffic but little incoming (response) traffic
  - May indicate destination host is overwhelmed

#### D-WARD: Observation Component

- Also aggregates traffic statistics to each remote address
- Classifies flows as attack, suspicious, normal
  - *Normal*: statistics match legitimate traffic model
  - *Attack*: if not
- Once traffic classified as attack begins to match legitimate traffic model, indicates attack has ended, so flow reclassified as *suspicious* 
  - If it stays suspicious for predetermined time, reclassified as normal

#### D-WARD: Rate-Limiting Component

- When attack detected, this component limits amount of packets that can be sent
- This reduces volume of traffic going from this network to destination
- How it limits rate is based on D-WARD's best guess of amount of traffic destination can handle
  - When flow reclassified as normal, D-WARD raises rate limit until sending rate is as before

### D-WARD: Traffic-Policing Component

- Component obtains information from other 2 components
- Based on this, decides whether to drop packets
  - Packets for normal connections always forwarded
  - Packets for other flows may be forwarded provided doing so does not exceed rate limit associated with flow