

ECS 289M Lecture 3

April 5, 2006

Overview

- Safety Question
- HRU Model
- Take-Grant Protection Model

What Is “Secure”?

- Adding a generic right r where there was not one is “leaking”
- If a system S , beginning in initial state s_0 , cannot leak right r , it is *safe with respect to the right r* .

Safety Question

- Does there exist an algorithm for determining whether a protection system S with initial state s_0 is safe with respect to a generic right r ?
 - Here, “safe” = “secure” for an abstract model

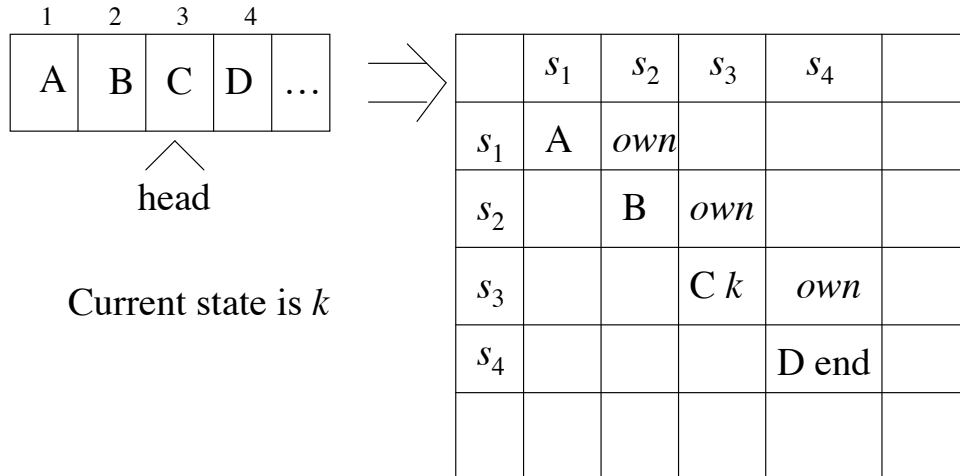
Mono-Operational Commands

- Answer: *yes*
 - Sketch of proof:
 - Consider minimal sequence of commands c_1, \dots, c_k to leak the right.
 - Can omit **delete**, **destroy**
 - Can merge all **creates** into one
- Worst case: insert every right into every entry; with s subjects and o objects initially, and n rights, upper bound is $k \leq n(s+1)(o+1)$

General Case

- Answer: *no*
- Sketch of proof:
 - Reduce halting problem to safety problem
 - Turing Machine review:
 - Infinite tape in one direction
 - States K , symbols M ; distinguished blank b
 - Transition function $\delta(k, m) = (k', m', L)$ means in state k , symbol m on tape location replaced by symbol m' , head moves to left one square, and enters state k'
 - Halting state is $q_{\hat{r}}$; TM halts when it enters this state

Mapping

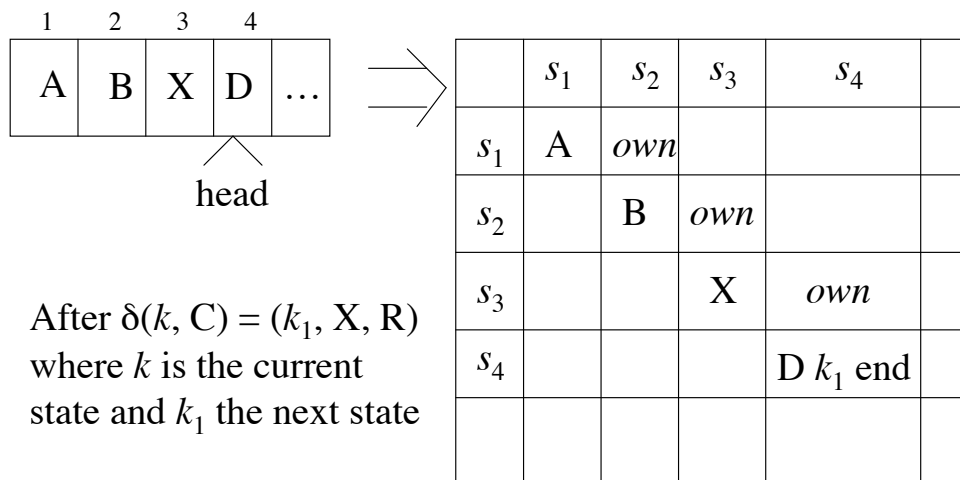


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Mapping



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Command Mapping

$\delta(k, C) = (k_1, X, R)$ at intermediate becomes

```

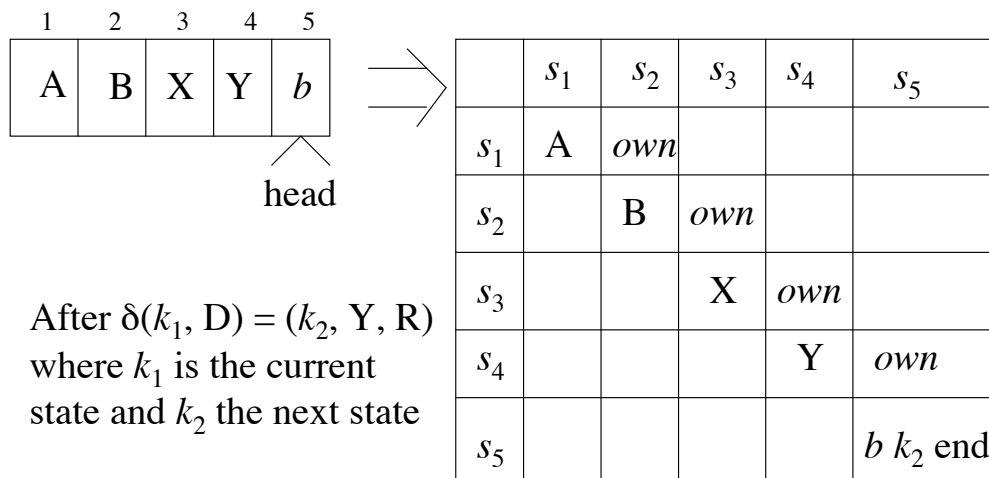
command  $c_{k,C}(s_3, s_4)$ 
if own in  $A[s_3, s_4]$  and  $k$  in  $A[s_3, s_3]$ 
    and  $C$  in  $A[s_3, s_3]$ 
then
    delete  $k$  from  $A[s_3, s_3]$ ;
    delete  $C$  from  $A[s_3, s_3]$ ;
    enter  $X$  into  $A[s_3, s_3]$ ;
    enter  $k_1$  into  $A[s_4, s_4]$ ;
end
    
```

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Mapping



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Command Mapping

$\delta(k_1, D) = (k_2, Y, R)$ at end becomes

```
command crighthmostk,c(s4, s5)  
if end in A[s4, s4] and k1 in A[s4, s4]  
    and D in A[s4, s4]  
then  
    delete end from A[s4, s4];  
    create subject s5;  
    enter own into A[s4, s5];  
    enter end into A[s5, s5];  
    delete k1 from A[s4, s4];  
    delete D from A[s4, s4];  
    enter Y into A[s4, s4];  
    enter k2 into A[s5, s5];  
end
```

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Rest of Proof

- Protection system exactly simulates a TM
 - Exactly 1 *end* right in ACM
 - 1 right in entries corresponds to state
 - Thus, at most 1 applicable command
- If TM enters state q_f , then right has leaked
- If safety question decidable, then represent TM as above and determine if q_f leaks
 - Implies halting problem decidable
- Conclusion: safety question undecidable

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Other Results

- Set of unsafe systems is recursively enumerable
- Delete **create** primitive; then safety question is complete in **P-SPACE**
- Delete **destroy**, **delete** primitives; then safety question is undecidable
 - Systems are monotonic
- Safety question for monoconditional, monotonic protection systems is decidable
- Safety question for monoconditional protection systems with **create**, **enter**, **delete** (and no **destroy**) is decidable.

Take-Grant Protection Model

- A specific (not generic) system
 - Set of rules for state transitions
- Safety decidable, and in time linear with the size of the system
- Goal: find conditions under which rights can be transferred from one entity to another in the system

System

- objects (files, ...)
- subjects (users, processes, ...)
- ⊗ don't care (either a subject or an object)

$G \mid\!-\!_x G'$ apply a rewriting rule x (witness) to G to get G'

$G \mid\!-\!^* G'$ apply a sequence of rewriting rules (witness) to G to get G'

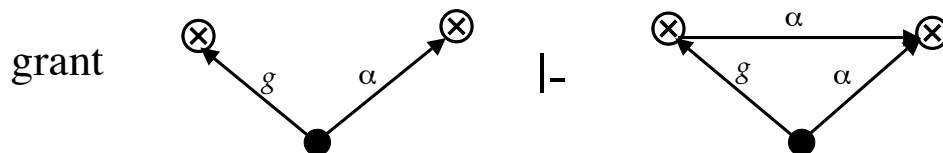
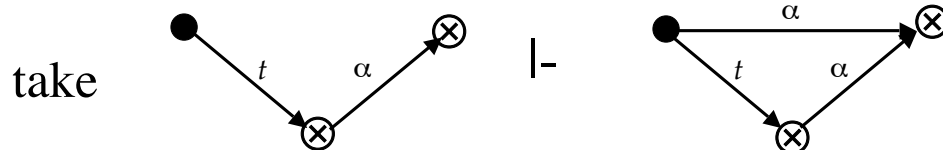
$R = \{ t, g, r, w, \dots \}$ set of rights

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Rules

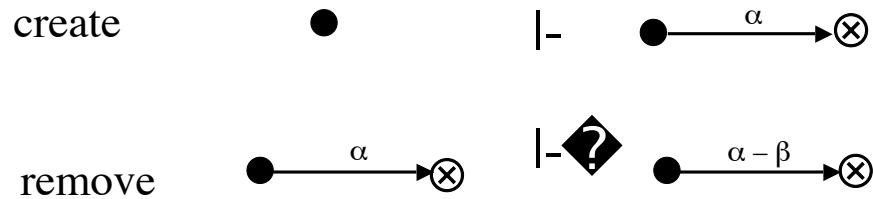


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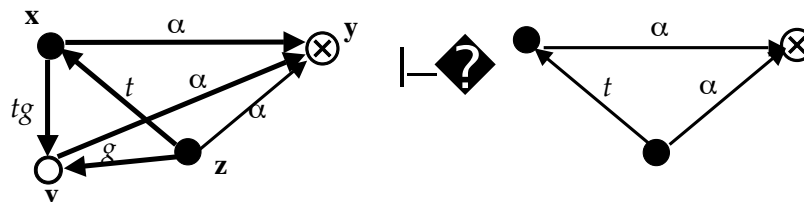
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More Rules



These four rules are called the *de jure* rules

Symmetry



1. **x** creates (*tg* to new) **v**
2. **z** takes (*g* to **v**) from **x**
3. **z** grants (α to **y**) to **v**
4. **x** takes (α to **y**) from **v**

Similar result for grant

Islands

- *tg*-path: path of distinct vertices connected by edges labeled *t* or *g*
 - Call them “*tg*-connected”
- island: maximal *tg*-connected subject-only subgraph
 - Any right one vertex has can be shared with any other vertex

Initial, Terminal Spans

- *initial span* from **x** to **y**
 - **x** subject
 - *tg*-path between **x**, **y** with word in $\{ t^*g \} \cup \{ \rightarrow \}$
 - Means **x** can give rights it has to **y**
- *terminal span* from **x** to **y**
 - **x** subject
 - *tg*-path between **x**, **y** with word in $\{ t^* \} \cup \{ v \}$
 - Means **x** can acquire any rights **y** has \rightarrow

Bridges

- bridge: tg -path between subjects \mathbf{x} , \mathbf{y} , with associated word in

$$\{ \overleftarrow{t}^*, \overrightarrow{t}^*, \overleftarrow{t}^* \overleftarrow{g} \overleftarrow{t}^*, \overrightarrow{t}^* \overrightarrow{g} \overrightarrow{t}^* \}$$

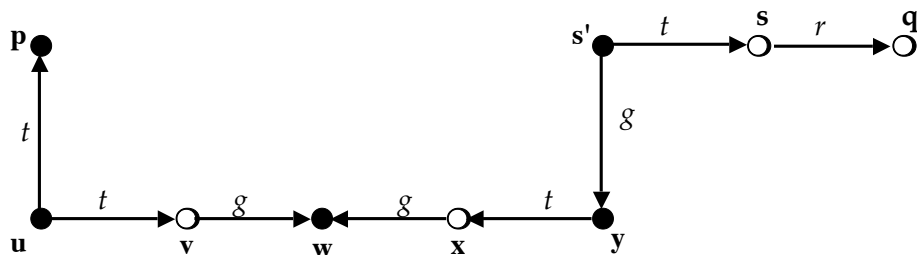
- rights can be transferred between the two endpoints
- *not* an island as intermediate vertices are objects

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Example



- islands $\{ p, u \}$ $\{ w \}$ $\{ y, s' \}$
- bridges u, v, w ; w, x, y
- initial span p (associated word v)
- terminal span s 's (associated word \overrightarrow{t})

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can•share Predicate

Definition:

- $can\bullet share(r, \mathbf{x}, \mathbf{y}, G_0)$ if, and only if, there is a sequence of protection graphs G_0, \dots, G_n such that $G_0 \dashv^* G_n$ using only *de jure* rules and in G_n there is an edge from \mathbf{x} to \mathbf{y} labeled r .

can•share Theorem

- $can\bullet share(r, \mathbf{x}, \mathbf{y}, G_0)$ if, and only if, there is an edge from \mathbf{x} to \mathbf{y} labeled r in G_0 , or the following hold simultaneously:
 - There is an \mathbf{s} in G_0 with an \mathbf{s} -to- \mathbf{y} edge labeled r
 - There is a subject $\mathbf{x}' = \mathbf{x}$ or initially spans to \mathbf{x}
 - There is a subject $\mathbf{s}' = \mathbf{s}$ or terminally spans to \mathbf{s}
 - There are islands I_1, \dots, I_k connected by bridges, and \mathbf{x}' in I_1 and \mathbf{s}' in I_k

Outline of Proof

- **s** has r rights over **y**
- **s'** acquires r rights over **y** from **s**
 - Definition of terminal span
- **x'** acquires r rights over **y** from **s'**
 - Repeated application of sharing among vertices in islands, passing rights along bridges
- **x'** gives r rights over **y** to **x**
 - Definition of initial span

Example Interpretation

- ACM is generic
 - Can be applied in any situation
- Take-Grant has specific rules, rights
 - Can be applied in situations matching rules, rights
- Question: what states can evolve from a system that is modeled using the Take-Grant Model?

Take-Grant Generated Systems

- Theorem: G_0 protection graph with 1 vertex, no edges; R set of rights. Then $G_0 \dashv^* G$ iff:
 - G finite directed graph consisting of subjects, objects, edges
 - Edges labeled from nonempty subsets of R
 - At least one vertex in G has no incoming edges

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Outline of Proof

- \Rightarrow : By construction; G final graph in theorem
- Let $\mathbf{x}_1, \dots, \mathbf{x}_n$ be subjects in G
 - Let \mathbf{x}_1 have no incoming edges
 - Now construct G' as follows:
 1. Do " \mathbf{x}_1 creates $(\alpha \cup \{g\}$ to) new subject \mathbf{x}_i "
 2. For all $(\mathbf{x}_i, \mathbf{x}_j)$ where \mathbf{x}_i has a rights over \mathbf{x}_j , do " \mathbf{x}_1 grants $(\alpha$ to $\mathbf{x}_j)$ to \mathbf{x}_i "
 3. Let β be rights \mathbf{x}_i has over \mathbf{x}_j in G . Do " \mathbf{x}_i removes $((\alpha \cup \{g\}) - \beta)$ to \mathbf{x}_j "
 - Now G' is desired G

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Outline of Proof

\Leftarrow : Let \mathbf{v} be initial subject, and $G_0 \vdash^* G$

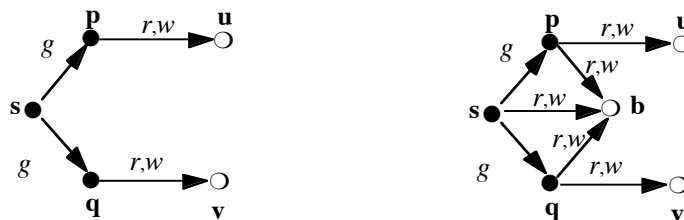
- Inspection of rules gives:
 - G is finite
 - G is a directed graph
 - Subjects and objects only
 - All edges labeled with nonempty subsets of R
- Limits of rules:
 - None allow vertices to be deleted so \mathbf{v} in G
 - None add incoming edges to vertices without incoming edges, so \mathbf{v} has no incoming edges

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Example: Shared Buffer



- Goal: \mathbf{p} , \mathbf{q} to communicate through shared buffer \mathbf{b} controlled by trusted entity \mathbf{s}
 1. \mathbf{s} creates ($\{r, w\}$ to new object) \mathbf{b}
 2. \mathbf{s} grants ($\{r, w\}$ to \mathbf{b}) to \mathbf{p}
 3. \mathbf{s} grants ($\{r, w\}$ to \mathbf{b}) to \mathbf{q}

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